

Probabilistic Logic Programming under the L-Stable Semantics

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Motivation: Inconsistencies in Probabilistic Logic Program

- ▶ **Probabilistic Answer Set Program (PASP)** eases the specification of intricate discrete statistical models involving relations, logical constraints, context-specific independence
- ▶ Interesting approach for **Neurosymbolic Reasoning** (probabilities are output of neural concept learners)
- ▶ Most semantics require **consistency** (no world is inconsistent)
- ▶ **Knowledge base construction** often produces inconsistencies (multiple experts, learned rules, unwanted worlds, etc)
- ▶ **L-Stable Semantics** gracefully handles inconsistencies while preserving essence of Distribution Semantics (Independent Probabilistic Facts + Logical Rules)
- ▶ [This Work](#): Complexity and Inference for PASP under L-Stable semantics

Answer Set Programming

An **answer set program** is a finite set of **extended disjunctive rules**:

head1; head2; ...; headM :- **pbody1, ..., pbodyN, not nbody1, ..., not nbodyO.**

- ▶ rule is a **fact** if body is empty
- ▶ program is **normal** if every rule has one atom in head
- ▶ we disallow integrity constraints (i.e., empty head rules)

Example: 3-coloring

```
% – FACTS  
node(1). node(2). node(3). node(4). edge(1,2). edge(2,3). edge(3,4). edge(1,4). edge(1,3).  
% – NORMAL RULE  
conflict(X,Y) :- not conflict(X,Y), edge(X,Y), color(X,C), color(Y,C).  
% – DISJUNCTIVE RULE  
color(X,red); color(X,blue); color(X,green) :- node(X).
```

L-Stable Semantics For Propositional Programs

- ▶ **Interpretation** assigns true/false/undefined to each atom (total if no undefined atom)
- ▶ Rule is **satisfied** if body is false, if body and head are true, or if body and head are undefined
- ▶ A **model** satisfies all rules
- ▶ **Partial stable model** if minimal model of program reduct (replace false/true/undefined literals in bodies with false/true/undefined)
- ▶ Partial stable model is **least undefined** (L-Stable) if there is no partial stable model defining more atoms

L-Stable Semantics

a; b.

a :- not a.

b :- not b.

id	$I(a), I(b)$	$P/I - \{a; b\}$	MinModels(P/I)
1	(false, false)	$a \leftarrow \text{true}. b \leftarrow \text{true}.$	(true, true)
2	(false, undef)	$a \leftarrow \text{true}. b \leftarrow \text{undef}.$	(true, undef)
3	(false, true)	$a \leftarrow \text{true}. b \leftarrow \text{false}.$	(true, false)
4	(undef, false)	$a \leftarrow \text{undef}. b \leftarrow \text{true}.$	(undef, true)
5	(undef, undef)	$a \leftarrow \text{undef}. b \leftarrow \text{undef}.$	(true, undef), (undef, true)
6	(undef, true)	$a \leftarrow \text{undef}. b \leftarrow \text{false}.$	(true, false), (undef, true)
7	(true, false)	$a \leftarrow \text{false}. b \leftarrow \text{true}.$	(false, true)
8	(true, undef)	$a \leftarrow \text{false}. b \leftarrow \text{undef}.$	(true, undef), (false, true)
9	(true, true)	$a \leftarrow \text{false}. b \leftarrow \text{false}.$	(true, false), (false, true)

Distribution Semantics [Dantsin 1990, Poole 1993, Fur 1995, Sato 1995]

- ▶ **Probabilistic Choices:** Collection of **fully independent** categorical RV's
- ▶ Each realization **generates** an ASP program

Probabilistic Answer Set Programming

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Random graph example: probabilistic program

```
node(1). node(2). node(3). 0.5::edge(1,2). 0.5::edge(2,3).
```

generates four programs, with **probability** $0.5 \times 0.5 = 0.25$ each:

```
node(1). node(2). node(3).
```

```
node(1). node(2). node(3). edge(1,2).
```

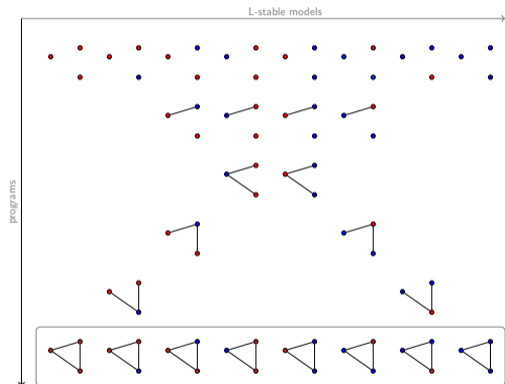
```
node(1). node(2). node(3). edge(2,3).
```

```
node(1). node(2). node(3). edge(1,2). edge(2,3).
```


Probabilistic Answer Set Programming Under L-Stable Semantics

Example: 2-colorability of random graph

```
% graph has 3 nodes...  
node(1). node(2). node(3).  
  
% and random edges.  
0.5::edge(X,Y) :- node(X), node(Y), X < Y.  
  
% color each node either red or blue  
color(X,red); color(X,blue) :- node(X).  
  
% such that no two endpoints have same color  
conflict(X,Y) :- edge(X,Y), color(X,C), color(Y,C).  
  
% graph is colorable iff no conflict  
conflict :- not conflict, conflict(X,Y).  
colorable :- not conflict.
```



$$\Pr(\text{colorable} = 1) = \sum_{\text{program}} 0.5^3 \times \Pr(\text{colorable} = 1 | \text{program}) = 1 - 0.5^3$$

Probabilistic Answer Set Programming: Probabilistic Semantics

$$\Pr(\text{atom}) = \sum_{\text{program}} \Pr(\text{program}) \sum_{\text{model} \models \text{atom}} \Pr(\text{model} \mid \text{program})$$

Distribution Semantics

Probabilistic Answer Set Programming: Probabilistic Semantics

$$\Pr(\text{atom}) = \sum_{\text{program}} \Pr(\text{program}) \sum_{\text{model} \models \text{atom}} \Pr(\text{model} \mid \text{program})$$

Distribution Semantics

- ▶ **Stratified:** each induced program has exactly one model
 - ▶ $\Pr(\text{model} \mid \text{program}) = 1$
- ▶ **Consistent:** induced programs have 1 or more models
 - ▶ Credal Semantics: consider the *credal set* of all distributions $\Pr(\text{model} \mid \text{program})$
 - ▶ MaxEnt: consider uniform $\Pr(\text{model} \mid \text{program}) = 1/\#\text{models}(\text{program})$
- ▶ **Plingo/LP^{MLN}:** Renormalize over consistent programs

► P1:

$$\min \Pr(\text{atom}) = \sum_{\substack{\text{program:} \\ \forall \text{model} \models \text{atom}}} \Pr(\text{program})$$

► P2:

$$\max \Pr(\text{atom}) = 1 - \min \Pr(\neg \text{atom})$$

► P3:

$$\min \Pr(a|b) = \frac{\min \Pr(a, b)}{\min \Pr(a, b) + \max \Pr(\neg a, b)}$$

Example: Credal and MaxEnt Semantics

0.1::a. 0.3::b.

c :- a. d :- b. c ; d. c :- not c. d :- not d.

	C	$\text{Pr}(\text{program}(C))$	$\text{LSModels}(\text{program}(C))$
1	\emptyset	0.63	(false, false, undef, true), (false, false, true, undef)
2	a	0.07	(true, false, true, undef)
3	b	0.27	(false, true, undef, true)
4	a, b	0.03	(true, true, true, true)

- ▶ Credal Semantics yields $\text{Pr}(c) \in [0.1, 0.73]$
- ▶ MaxEnt Semantics yields $\text{Pr}(c) = 0.415$
- ▶ Both semantics assign $\text{Pr}(\text{not } c) = 0$

Inference Complexity under Stable Semantics

- ▶ **Credal Semantics:** $\min \Pr(\text{atom}|\text{evidence})$
 - ▶ $\text{PP}^{\Sigma_2^P}$ -hard for propositional programs with disjunction and negation/aggregates
 - ▶ PP^{NP} -hard for disjunction-free, aggregate-free propositional programs
 - ▶ PP-hard for stratified propositional programs
 - ▶ One step higher in Counting Hierarchy for relational programs with bounded-arity predicates (e.g., $\text{PP}^{\Sigma_3^P}$ -hard for disjunctive programs)
 - ▶ EXPTIME if predicate arity is unbounded
- ▶ **MaxEnt Semantics:** $\Pr(\text{atom}|\text{evidence})$
 - ▶ PP-hard, from stratified programs

Theorem (Mauá & Cozman, 2020)

If consistency in some logic programming language belongs to complexity class C , then probabilistic inference under the credal semantics in the corresponding probabilistic logic programming language belongs to PP^C .

- ▶ Consistency in **propositional normal programs** is Σ_2^P -complete [Eiter, Leone & Saccà 1998]
- ▶ Consistency in **propositional disjunctive programs** is Σ_3^P -complete [ELS 98]

Theorem

*Deciding if there is an L-stable model satisfying a given atom for a **normal program** with bounded-arity predicates is Σ_3^P -hard.*

Proof. Reduction from 3-QBF with least undefinedness encoding boolean quantifier.

$$\exists X_1, \dots, X_m \forall X_{m+1}, \dots, X_n \exists X_{n+1}, \dots, X_p \phi(X_1, \dots, X_p),$$

Theorem

*Deciding if there is an L-stable model satisfying a given atom for a **disjunctive program** with bounded-arity predicates is Σ_4^P -hard.*

Proof. Reduction from 4-QBF using saturation and least undefinedness.

Corollary

Probabilistic inference in *propositional disjunctive programs* under the credal L-stable semantics predicates is $PP^{\Sigma_3^P}$ -complete.

Corollary

Probabilistic inference in *normal probabilistic programs* with bounded-arity predicates under the credal L-stable semantics is $PP^{\Sigma_3^P}$ -complete.

Corollary

Probabilistic inference in *disjunctive probabilistic programs* with bounded-arity predicates under the credal L-stable semantics is $PP^{\Sigma_4^P}$ -complete.

Contributions: Complexity under MaxEnt L-Stable Semantics

- ▶ Theorem of Mauá & Cozman 2021 doesn't apply for MaxEnt semantics (AFIK)
- ▶ Hence need of more direct proof
- ▶ Lack of inner decision problem makes result challenging

Contributions: Complexity under MaxEnt L-Stable Semantics

- ▶ Theorem of Mauá & Cozman 2021 doesn't apply for MaxEnt semantics (AFIK)
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- ▶ Lack of inner decision problem makes result challenging

Theorem

*Deciding whether the probability of an atom exceeds a given threshold under the MaxEnt semantics for **propositional disjunctive programs** is PP-complete when the L-stable models of any induced logic program are **efficiently enumerated**.*

Proof. Hardness follows from stratified programs. Membership: Use no. of models to build Turing machine.

Theorem

*Deciding if the probability of an atom exceeds a given threshold under the MaxEnt semantics for **disjunctive programs with bounded-arity predicates** is in PP^{PP} .*

Proof. Build Turing machine and count with precision proportional to input size. Use integer gap to decide.

Theorem

*Deciding if the probability of an atom exceeds a given threshold under the MaxEnt semantics for **propositional normal programs** is PP^{NP} -hard, even if all atoms are defined.*

Proof. Reduction from MAJ-E-SAT using integer gap in count to decide E-SAT part.

Probabilistic Inference under the L-Stable Semantics

Janhunen et al. 2006's Translation from L-stable to Stable

$a ; b.$

$a :- \text{not } a.$

$b :- \text{not } b.$

$a ; b. \quad _a ; _b.$

$a :- \text{not } _a. \quad _a :- \text{not } a. \quad _a :- a.$

$b :- \text{not } _b. \quad _b :- \text{not } b. \quad _b :- b.$

id	$I(a), I(\underline{a}), I(b), I(\underline{b})$	$P/I - P'$	$\text{MinModels}(P/I)$
3	(false, false, true, true)	$a \leftarrow \text{true}. \underline{a} \leftarrow \text{true}. b \leftarrow \text{false}. \underline{b} \leftarrow \text{false}.$	(true, true, false, false)
6	(false, true, true, true)	$a \leftarrow \text{false}. \underline{a} \leftarrow \text{true}. b \leftarrow \text{false}. \underline{b} \leftarrow \text{false}.$	(true, true, false, false), (false, true, true, true)
7	(true, true, false, false)	$a \leftarrow \text{false}. \underline{a} \leftarrow \text{false}. b \leftarrow \text{true}. \underline{b} \leftarrow \text{true}.$	(false, false, true, true)
8	(true, true, false, true)	$a \leftarrow \text{false}. \underline{a} \leftarrow \text{false}. b \leftarrow \text{false}. \underline{b} \leftarrow \text{true}.$	(true, true, false, true), (false, false, true, true)
9	(true, true, true, true)	$a \leftarrow \text{false}. \underline{a} \leftarrow \text{false}. b \leftarrow \text{false}. \underline{b} \leftarrow \text{false}.$	(true, true, false, false), (false, false, true, true)

Note: atom is undefined iff x and \underline{x} disagree

We have implemented the inference algorithm in our comprehensive neuro-probabilistic-logic framework called dPASP:

<http://github.com/kamel-usp/dpasp>

Inconsistent example program:

```
person(1..4).
0.1::asthma(X).      0.3::stress(X).
0.3::influences(1,2). 0.6::influences(2,1).
0.2::influences(2,3). 0.7::influences(3,4).
0.9::influences(4,1).
0.6::inh_stress(X). 0.6::inh_smokes(X).
smokes_pos(X) :- stress(X), not inh_stress(X).
asthma(X) :- smokes(X), not inh_smokes(X).
smokes_pos(X) :- influences(Y,X), smokes(Y).
smokes_neg(X) :- asthma(X).
smokes(X) :- smokes_pos(X), not smokes_neg(X).
```

Semantics	Pr(smokes(X) = undef)			
	1	2	3	4
smProbLog	0.2223	0.2223	0.2223	0.2223
L-stable	0.1548	0.0828	0.0599	0.0909

- ▶ L-Stable semantics is less undefined
- ▶ Preserves independence of probabilistic choices

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